Lecture 11: Panel data I

PPHA 34600 Prof. Fiona Burlig

Harris School of Public Policy University of Chicago Z_i is a valid instrument when the following are satisfied:

- **1** First stage: $Cov(Z_i, D_i) \neq 0$
- **2** Exclusion restriction: $Cov(Z_i, \varepsilon_i) = 0$

When we have these two conditions, we can...:

- Estimate causal effects
- ...but only for compliers!

So far, we've focused on data across units. Now we'll add time:

• Cross-sectional data:

- What we've been using
- Observations across units at a single point in time

So far, we've focused on data across units. Now we'll add time:

• Cross-sectional data:

- What we've been using
- Observations across units at a single point in time

• Time series data:

• Observations on a single unit over time

So far, we've focused on data across units. Now we'll add time:

• Cross-sectional data:

- What we've been using
- Observations across units at a single point in time

• Time series data:

• Observations on a single unit over time

• Repeated cross-section data:

• Repeated sampling of different units over time

So far, we've focused on data across units. Now we'll add time:

• Cross-sectional data:

- What we've been using
- Observations across units at a single point in time

• Time series data:

• Observations on a single unit over time

• Repeated cross-section data:

• Repeated sampling of different units over time

• Panel data:

• Multiple observations of the same unit over time

Why is data over time useful?

We've spilled a lot of ink on the selection problem:

• To isolate the effect of D_i , we need potential outcomes to be the same among treated and untreated units

Why is data over time useful?

We've spilled a lot of ink on the selection problem:

- To isolate the effect of D_i , we need potential outcomes to be the same among treated and untreated units
- With cross-sectional data, this is fundamentally tricky:
 - People, firms, households, etc are different from one another in lots of ways
 - Getting a clean comparison means separating τ from all of these differences

Why is data over time useful?

We've spilled a lot of ink on the selection problem:

- To isolate the effect of D_i , we need potential outcomes to be the same among treated and untreated units
- With cross-sectional data, this is fundamentally tricky:
 - People, firms, households, etc are different from one another in lots of ways
 - Getting a clean comparison means separating τ from all of these differences
- Enter <u>time series data</u>:
 - Fundamental insight: Rather than comparing *i* to *j*, compare *i* in *t* to *i* in *t* - 1
 - In this formulation, *i* serves as a control for itself
 - *i* am much more similar to myself yesterday than *i* am to *j*

Making time-series comparisons

Consider a setting with only one unit:

- We now denote our outcome as $Y_t(D_t)$ (no subscript: only one unit)
- As usual, we want to estimate $\tau^{ATE} = E[Y_t(D_t = 1) Y_t(D_t = 0)]$
- But we can't observe both $Y_{t=1}(D_{t=1}=1)$ and $Y_{t=1}(D_{t=1}=0)$
 - $\rightarrow\,$ Remember that fundamental problem of causal inference?

Making time-series comparisons

Consider a setting with only one unit:

- We now denote our outcome as $Y_t(D_t)$ (no subscript: only one unit)
- As usual, we want to estimate $au^{ATE} = E[Y_t(D_t = 1) Y_t(D_t = 0)]$
- But we can't observe both $Y_{t=1}(D_{t=1}=1)$ and $Y_{t=1}(D_{t=1}=0)$

 \rightarrow Remember that fundamental problem of causal inference?

- Instead, we look for periods before and after treatment begins
- Suppose in t = 0, $D_{t=0} = 0$, and in t = 1, $D_{t=1} = 1$
- Then we can estimate:

$$\hat{\tau}^{TS} = Y_{t=1} - Y_{t=0}$$

Making time-series comparisons

Consider a setting with only one unit:

- We now denote our outcome as $Y_t(D_t)$ (no subscript: only one unit)
- As usual, we want to estimate $au^{ATE} = E[Y_t(D_t = 1) Y_t(D_t = 0)]$
- But we can't observe both $Y_{t=1}(D_{t=1}=1)$ and $Y_{t=1}(D_{t=1}=0)$

 \rightarrow Remember that fundamental problem of causal inference?

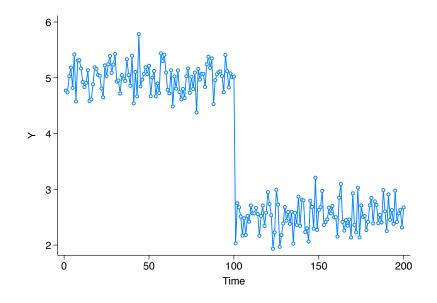
- Instead, we look for periods before and after treatment begins
- Suppose in t = 0, $D_{t=0} = 0$, and in t = 1, $D_{t=1} = 1$
- Then we can estimate:

$$\hat{\tau}^{TS} = Y_{t=1} - Y_{t=0}$$

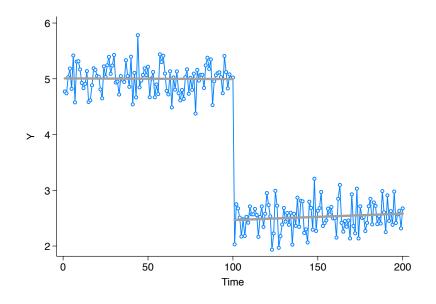
• We can also extend this to many periods:

$$\hat{\tau}^{TS} = \bar{Y}_{t \in \text{post}} - \bar{Y}_{t \in \text{pre}}$$

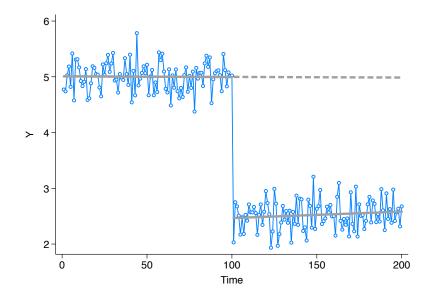
Time series, visually



Time series, visually



Time series, visually



What's good about the time series?

This time series approach compares unit *i* to itself over time:

• Consider a simple data-generating process:

$$Y_{it} = \beta_i X_i$$

• In this model, we have time-invariant characteristics (X_i)

What's good about the time series?

This time series approach compares unit *i* to itself over time:

• Consider a simple data-generating process:

$$Y_{it} = \beta_i X_i$$

- In this model, we have time-invariant characteristics (X_i)
- Now add treatment:

$$Y_{it} = \tau D_{it} + \beta X_i$$

where $D_{it} = 0$ in t = 0 and $D_{it} = 1$ in t = 1

We want to separate treatment from the other characteristics

What's good about the time series?

This time series approach compares unit *i* to itself over time:

• Consider a simple data-generating process:

$$Y_{it} = \beta_i X_i$$

- In this model, we have time-invariant characteristics (X_i)
- Now add treatment:

$$Y_{it} = \tau D_{it} + \beta X_i$$

where $D_{it} = 0$ in t = 0 and $D_{it} = 1$ in t = 1

- We want to separate treatment from the other characteristics
- Enter the difference estimator:

$$egin{aligned} Y_{i,t=1} - Y_{i,t=0} &= au(D_{i,t=1} - D_{i,t=0}) + eta(X_i - X_i) \ &= au(D_{i,t=1} - D_{i,t=0}) \ &= au(1-0) \end{aligned}$$

PPHA 34600

We can pull the same trick with unobservables

• Consider a simple data-generating process:

 $Y_{it} = \beta X_i + \gamma U_i$

- In this model, we have time-invariant observable characteristics (X_i)
- We also have time-invariant unobserved characteristics (U_i)

We can pull the same trick with unobservables

• Consider a simple data-generating process:

 $Y_{it} = \beta X_i + \gamma U_i$

- In this model, we have time-invariant observable characteristics (X_i)
- We also have time-invariant unobserved characteristics (U_i)
- Now add treatment:

$$Y_{it} = \tau D_{it} + \beta X_i + \gamma U_i$$

where $D_{it} = 0$ in t = 0 and $D_{it} = 1$ in t = 1

• We want to separate treatment from the other characteristics

We can pull the same trick with unobservables

• Consider a simple data-generating process:

 $Y_{it} = \beta X_i + \gamma U_i$

- In this model, we have time-invariant observable characteristics (X_i)
- We also have time-invariant unobserved characteristics (U_i)
- Now add treatment:

$$Y_{it} = \tau D_{it} + \beta X_i + \gamma U_i$$

where $D_{it} = 0$ in t = 0 and $D_{it} = 1$ in t = 1

- We want to separate treatment from the other characteristics
- Enter the difference estimator:

$$Y_{i,t=1} - Y_{i,t=0} = \tau(D_{i,t=1} - D_{i,t=0}) + \beta(X_i - X_i) + \gamma(U_i - U_i)$$

= $\tau(D_{i,t=1} - D_{i,t=0})$
= τ

In order for

$$\hat{\tau}^{TS} = Y_{i,t=1} - Y_{i,t=0}$$

to recover the true τ , we need an important assumption. Consider the DGP:

$$Y_{it} = \tau D_{it} + \beta X_i + \gamma U_i + \delta V_{it}$$

where V_{it} is a set of observed and unobserved **time-varying** characteristics

In order for

$$\hat{\tau}^{TS} = Y_{i,t=1} - Y_{i,t=0}$$

to recover the true $\tau,$ we need an important assumption. Consider the DGP:

$$Y_{it} = \tau D_{it} + \beta X_i + \gamma U_i + \delta V_{it}$$

where V_{it} is a set of observed and unobserved **time-varying** characteristics In this case,

$$\hat{\tau}^{TS} = Y_{i,t=1} - Y_{i,t=0} = \tau + \delta(V_{i,t=1} - V_{i,t=0})$$

In order for $\hat{\tau}^{TS}$ to equal τ , we need $\delta = 0$ or $V_{i,t=1} = V_{i,t=0} (= V_i)$

In order for

$$\hat{\tau}^{TS} = Y_{i,t=1} - Y_{i,t=0}$$

to recover the true $\tau,$ we need an important assumption. Consider the DGP:

$$Y_{it} = \tau D_{it} + \beta X_i + \gamma U_i + \delta V_{it}$$

where V_{it} is a set of observed and unobserved **time-varying** characteristics In this case,

$$\hat{\tau}^{TS} = Y_{i,t=1} - Y_{i,t=0} = \tau + \delta(V_{i,t=1} - V_{i,t=0})$$

In order for $\hat{\tau}^{TS}$ to equal τ , we need $\delta = 0$ or $V_{i,t=1} = V_{i,t=0} (= V_i)$

\rightarrow Any time-varying variables will create bias in $\hat{\tau}^{TS}$

 \rightarrow Also true for observables: we can't separate D_{it} from coincident V_{it}

- Y_i would be unchanged in the absence of treatment
- To see this, we can write:

$$\hat{\tau}^{TS} = Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)$$

- Y_i would be unchanged in the absence of treatment
- To see this, we can write:

$$\hat{\tau}^{TS} = Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) + (Y_{i,t=1}(0) - Y_{i,t=1}(0))$$

- Y_i would be unchanged in the absence of treatment
- To see this, we can write:

$$\hat{\tau}^{TS} = Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) + (Y_{i,t=1}(0) - Y_{i,t=1}(0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=1}(0)) + (Y_{i,t=1}(0) - Y_{i,t=0}(0))$$

- Y_i would be unchanged in the absence of treatment
- To see this, we can write:

$$\hat{\tau}^{TS} = Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) + (Y_{i,t=1}(0) - Y_{i,t=1}(0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=1}(0)) + (Y_{i,t=1}(0) - Y_{i,t=0}(0))$$

$$\approx E[Y_{i,t=1}(1) - Y_{i,t=1}(0)|D_i = 1] + E[Y_{i,t=1}(0) - Y_{i,t=0}(0)|D_i = 1]$$

Another way to think about this assumption:

- Y_i would be unchanged in the absence of treatment
- To see this, we can write:

$$\hat{\tau}^{TS} = Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) + (Y_{i,t=1}(0) - Y_{i,t=1}(0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=1}(0)) + (Y_{i,t=1}(0) - Y_{i,t=0}(0))$$

 $\approx E[Y_{i,t=1}(1) - Y_{i,t=1}(0)|D_i = 1] + E[Y_{i,t=1}(0) - Y_{i,t=0}(0)|D_i = 1]$

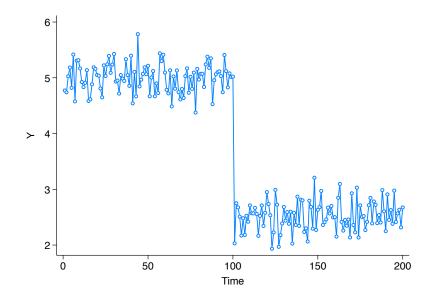
 $= \tau + \text{counterfactual trend}$

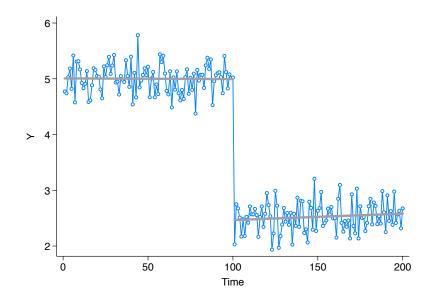
We have to assume that the counterfactual trend is zero

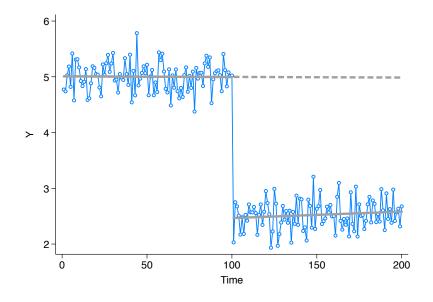
PPHA 34600

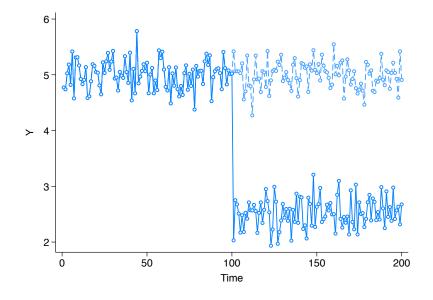
Program Evaluation

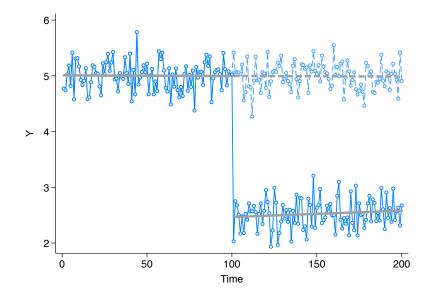
Lecture 11 9 / 21

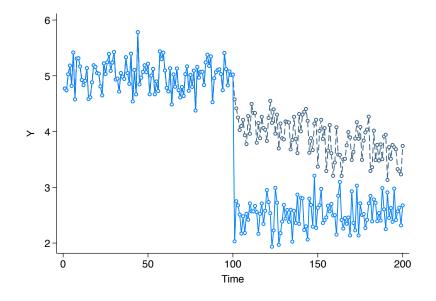


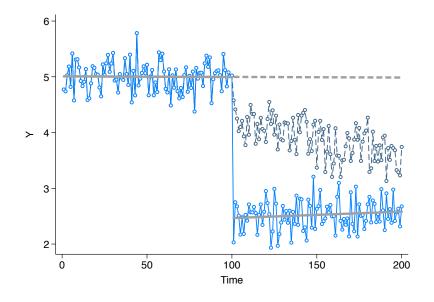












Validating the identifying assumption

We can never prove the identifying assumption:

- To do this, we would need to observe the counterfactual
- We can't do this ightarrow no test (2)

Validating the identifying assumption

We can never prove the identifying assumption:

- To do this, we would need to observe the counterfactual
- We can't do this ightarrow no test ($\regate{}$)
- You could try to look at pre-treatment trends...
- ...but this is likely unsatsifying

Validating the identifying assumption

We can never prove the identifying assumption:

- To do this, we would need to observe the counterfactual
- We can't do this ightarrow no test ($\regate{}$)
- You could try to look at pre-treatment trends...
- ...but this is likely unsatsifying

Why does this matter?

- If the assumption is not satisfied, we will confound the trend with $\boldsymbol{\tau}$
- We cannot eliminate the trend with one time series

Two wrongs make a right?

Using panel data, we can combine two bad estimators into a good one:

- Our naive (cross-sectional) estimator:
 - Compare *i* to *j* (static)
 - Suffers from selection bias (*i* and *j* are systematically different)

Two wrongs make a right?

Using panel data, we can combine two bad estimators into a good one:

- Our naive (cross-sectional) estimator:
 - Compare *i* to *j* (static)
 - Suffers from selection bias (*i* and *j* are systematically different)
- The time-series estimator:
 - Compare *i* to itself over time
 - Suffers from time-varying unobservables
 - AKA non-zero trends

Two wrongs make a right?

Using panel data, we can combine two bad estimators into a good one:

- Our naive (cross-sectional) estimator:
 - Compare *i* to *j* (static)
 - Suffers from selection bias (*i* and *j* are systematically different)
- The time-series estimator:
 - Compare *i* to itself over time
 - Suffers from time-varying unobservables
 - AKA non-zero trends
- We can combine these into the difference-in-differences estimator:
 - Uses across-unit, within time, comparisons
 - And within-unit, across time, comparisons

The problem with time series is the counterfactual trend:

- How would treated *i* have behaved in t = 1 without treatment?
- This is the missing counterfactual
- Using other individuals *j*, we can make a guess

The problem with time series is the counterfactual trend:

- How would treated *i* have behaved in t = 1 without treatment?
- This is the missing counterfactual
- Using other individuals *j*, we can make a guess

The differences-in-differences estimator:

$$\hat{\tau}^{DD} = \hat{\tau}_{D_i=1}^{TS} - \hat{\tau}_{D_i=0}^{TS}$$

The problem with time series is the counterfactual trend:

- How would treated *i* have behaved in *t* = 1 without treatment?
- This is the missing counterfactual
- Using other individuals j, we can make a guess

The differences-in-differences estimator:

$$\hat{\tau}^{DD} = \hat{\tau}_{D_i=1}^{TS} - \hat{\tau}_{D_i=0}^{TS}$$

 $= (Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)) - (Y_{j,t=1}(D_{jt} = 0) - Y_{i,t=0}(D_{jt} = 0))$

The problem with time series is the counterfactual trend:

- How would treated *i* have behaved in t = 1 without treatment?
- This is the missing counterfactual
- Using other individuals j, we can make a guess

The differences-in-differences estimator:

$$\hat{\tau}^{DD} = \hat{\tau}_{D_i=1}^{TS} - \hat{\tau}_{D_i=0}^{TS}$$

 $= (Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)) - (Y_{j,t=1}(D_{jt} = 0) - Y_{i,t=0}(D_{jt} = 0))$

 $= (Y(D_i = 1, post) - Y(D_i = 1, pre)) - (Y(D_i = 0, post) - Y(D_i = 0, pre))$

The problem with time series is the counterfactual trend:

- How would treated *i* have behaved in *t* = 1 without treatment?
- This is the missing counterfactual
- Using other individuals j, we can make a guess

The differences-in-differences estimator:

$$\hat{\tau}^{DD} = \hat{\tau}_{D_i=1}^{TS} - \hat{\tau}_{D_i=0}^{TS}$$

 $= (Y_{i,t=1}(D_{it} = 1) - Y_{i,t=0}(D_{it} = 0)) - (Y_{j,t=1}(D_{jt} = 0) - Y_{i,t=0}(D_{jt} = 0))$

 $= (Y(D_i = 1, post) - Y(D_i = 1, pre)) - (Y(D_i = 0, post) - Y(D_i = 0, pre))$

This compares treated to untreated units over time

PPHA 34600

Consider a simple data-generating process:

 $Y_{it} = \beta X_i + \delta S_t$

• We have time-invariant characteristics (X_i) and time-varying S_t

Consider a simple data-generating process:

$$Y_{it} = \beta X_i + \delta S_t$$

- We have time-invariant characteristics (X_i) and time-varying S_t
- Now add treatment (only for unit *i*):

$$Y_{it} = \tau D_{it} + \beta X_i + \delta S_t$$
$$Y_{jt} = \beta X_j + \delta S_t$$

Consider a simple data-generating process:

$$Y_{it} = \beta X_i + \delta S_t$$

- We have time-invariant characteristics (X_i) and time-varying S_t
- Now add treatment (only for unit *i*):

$$Y_{it} = \tau D_{it} + \beta X_i + \delta S_t$$
$$Y_{jt} = \beta X_j + \delta S_t$$

• Enter the DD estimator:

$$Y_{i,t=1} - Y_{i,t=0} = \tau (D_{i,t=1} - D_{i,t=0}) + \beta (X_i - X_i) + \delta (S_{t=1} - S_{t=0})$$
$$Y_{j,t=1} - Y_{j,t=0} = \beta (X_j - X_j) + \delta (S_{t=1} - S_{t=0})$$

Consider a simple data-generating process:

$$Y_{it} = \beta X_i + \delta S_t$$

- We have time-invariant characteristics (X_i) and time-varying S_t
- Now add treatment (only for unit *i*):

$$Y_{it} = \tau D_{it} + \beta X_i + \delta S_t$$
$$Y_{jt} = \beta X_j + \delta S_t$$

Enter the DD estimator:

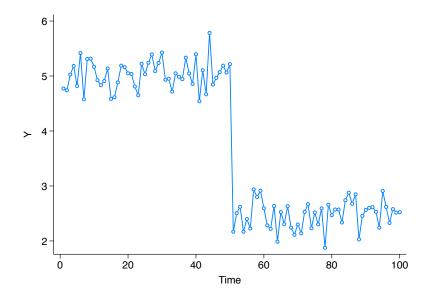
$$Y_{i,t=1} - Y_{i,t=0} = \tau(D_{i,t=1} - D_{i,t=0}) + \beta(X_i - X_i) + \delta(S_{t=1} - S_{t=0})$$
$$Y_{j,t=1} - Y_{j,t=0} = \beta(X_j - X_j) + \delta(S_{t=1} - S_{t=0})$$

$$\hat{\tau}^{DD} = (Y_{i,t=1} - Y_{i,t=0}) - (Y_{j,t=1} - Y_{j,t=0})$$

= $\tau (D_{i,t=1} - D_{i,t=0}) = \tau$

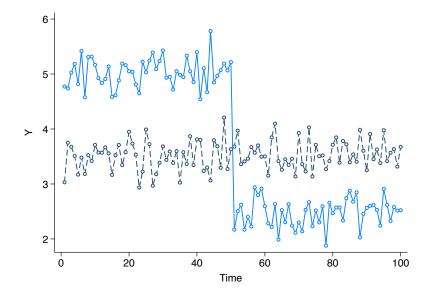
Program Evaluation

DD, visually

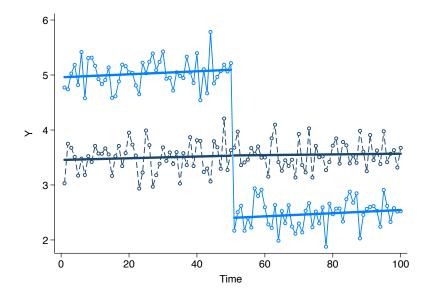


```
PPHA 34600
```

DD, visually



DD, visually



```
PPHA 34600
```

The identifying assumption of the DD is "parallel trends":

 $\hat{\tau}^{DD} = (Y_{i,t=1}(D_{it}=1) - Y_{i,t=0}(D_{it}=0)) - (Y_{j,t=1}(D_{jt}=0) - Y_{j,t=0}(D_{jt}=0))$

The identifying assumption of the DD is "parallel trends":

$$\hat{\tau}^{DD} = (Y_{i,t=1}(D_{it}=1) - Y_{i,t=0}(D_{it}=0)) - (Y_{j,t=1}(D_{jt}=0) - Y_{j,t=0}(D_{jt}=0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))$$

The identifying assumption of the DD is "parallel trends":

$$\hat{\tau}^{DD} = (Y_{i,t=1}(D_{it}=1) - Y_{i,t=0}(D_{it}=0)) - (Y_{j,t=1}(D_{jt}=0) - Y_{j,t=0}(D_{jt}=0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))$$

$$+(Y_{i,t=1}(0) - Y_{i,t=1}(0))$$

The identifying assumption of the DD is "parallel trends":

$$\hat{\tau}^{DD} = (Y_{i,t=1}(D_{it}=1) - Y_{i,t=0}(D_{it}=0)) - (Y_{j,t=1}(D_{jt}=0) - Y_{j,t=0}(D_{jt}=0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))$$

$$+(Y_{i,t=1}(0) - Y_{i,t=1}(0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=1}(0)) + [(Y_{i,t=1}(0) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))]$$

The identifying assumption of the DD is "parallel trends":

$$\hat{\tau}^{DD} = (Y_{i,t=1}(D_{it}=1) - Y_{i,t=0}(D_{it}=0)) - (Y_{j,t=1}(D_{jt}=0) - Y_{j,t=0}(D_{jt}=0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))$$

 $+(Y_{i,t=1}(0) - Y_{i,t=1}(0))$

$$= (Y_{i,t=1}(1) - Y_{i,t=1}(0)) + [(Y_{i,t=1}(0) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))]$$

$$\approx E[Y_{i,t=1}(1) - Y_{i,t=1}(0)|D_i = 1] + E[Y_{i,t=1}(0) - Y_{i,t-1}(0)|D_i = 1] \\ -E[Y_{j,t=1}(0) - Y_{j,t=0}(0)|D_j = 0]$$

The identifying assumption of the DD is "parallel trends":

$$\hat{\tau}^{DD} = (Y_{i,t=1}(D_{it}=1) - Y_{i,t=0}(D_{it}=0)) - (Y_{j,t=1}(D_{jt}=0) - Y_{j,t=0}(D_{jt}=0))$$

$$= (Y_{i,t=1}(1) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))$$

 $+(Y_{i,t=1}(0) - Y_{i,t=1}(0))$

$$= (Y_{i,t=1}(1) - Y_{i,t=1}(0)) + [(Y_{i,t=1}(0) - Y_{i,t=0}(0)) - (Y_{j,t=1}(0) - Y_{j,t=0}(0))]$$

$$pprox E[Y_{i,t=1}(1) - Y_{i,t=1}(0)|D_i = 1] + E[Y_{i,t=1}(0) - Y_{i,t-1}(0)|D_i = 1] \ - E[Y_{j,t=1}(0) - Y_{j,t=0}(0)|D_j = 0]$$

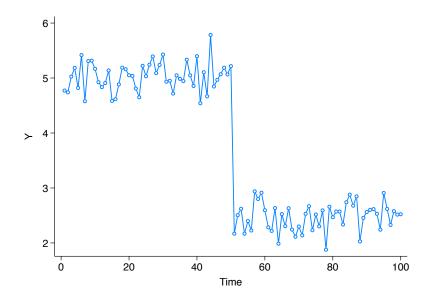
 $= \tau + {\rm counterfactual \ trend} - {\rm untreated \ trend}$

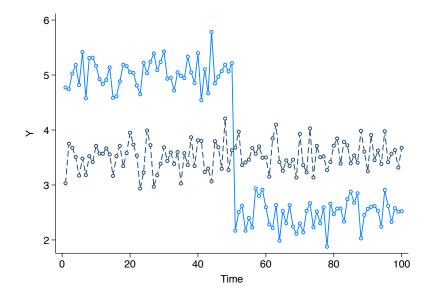
Identifying assumption: untreated trend = counterfactual trend

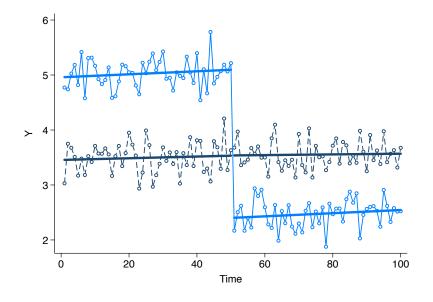
PPHA 34600

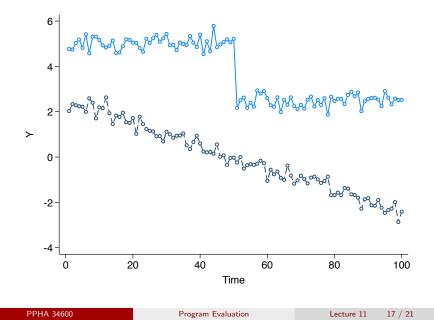
Program Evaluation

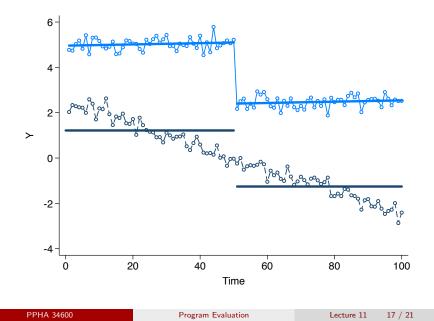
Lecture 11 16 / 21











The simplest implementation of DD is just:

 $\hat{\tau}^{DD} = (\bar{Y}(\textit{treat},\textit{post}) - \bar{Y}(\textit{treat},\textit{pre})) - (\bar{Y}(\textit{untreat},\textit{post}) - \bar{Y}(\textit{untreat},\textit{pre}))$

The simplest implementation of DD is just:

 $\hat{\tau}^{DD} = (\bar{Y}(\textit{treat},\textit{post}) - \bar{Y}(\textit{treat},\textit{pre})) - (\bar{Y}(\textit{untreat},\textit{post}) - \bar{Y}(\textit{untreat},\textit{pre}))$

We can implement this via the following regression:

$$Y_i = lpha + au$$
 Treat $imes$ Post_{it} + eta Treat_i + δ Post_t + ε_{it}

The simplest implementation of DD is just:

 $\hat{\tau}^{DD} = (\bar{Y}(\textit{treat},\textit{post}) - \bar{Y}(\textit{treat},\textit{pre})) - (\bar{Y}(\textit{untreat},\textit{post}) - \bar{Y}(\textit{untreat},\textit{pre}))$

We can implement this via the following regression:

$$Y_i = \alpha + \tau \operatorname{Treat} \times \operatorname{Post}_{it} + \beta \operatorname{Treat}_i + \delta \operatorname{Post}_t + \varepsilon_{it}$$

To link these together, see:

$$\overline{Y}(treat, post) = \hat{\alpha} + \hat{\tau} + \hat{\beta} + \hat{\delta}$$

 $\overline{Y}(treat, pre) = \hat{\alpha} + \hat{\beta}$
 $\rightarrow \overline{Y}(treat, post) - \overline{Y}(treat, pre) = \hat{\delta} + \hat{\tau}$

The simplest implementation of DD is just:

$$\hat{ au}^{DD} = (ar{Y}(extsf{treat}, extsf{post}) - ar{Y}(extsf{treat}, extsf{pre})) - (ar{Y}(extsf{untreat}, extsf{post}) - ar{Y}(extsf{untreat}, extsf{pre}))$$

We can implement this via the following regression:

$$Y_i = \alpha + \tau \operatorname{Treat} imes \operatorname{Post}_{it} + \beta \operatorname{Treat}_i + \delta \operatorname{Post}_t + \varepsilon_{it}$$

To link these together, see:

$$\bar{Y}(treat, post) = \hat{\alpha} + \hat{\tau} + \hat{\beta} + \hat{\delta}$$

 $\bar{Y}(treat, pre) = \hat{\alpha} + \hat{\beta}$
 $\rightarrow \bar{Y}(treat, post) - \bar{Y}(treat, pre) = \hat{\delta} + \hat{\tau}$
and
 $\bar{Y}(untreat, post) = \hat{\alpha} + \hat{\delta}$
 $\bar{Y}(untreat, pre) = \hat{\alpha}$
 $\rightarrow \bar{Y}(untreat, post) - \bar{Y}(untreat, pre) = \hat{\delta}$

The simplest implementation of DD is just:

 $\hat{\tau}^{DD} = (\bar{Y}(\textit{treat},\textit{post}) - \bar{Y}(\textit{treat},\textit{pre})) - (\bar{Y}(\textit{untreat},\textit{post}) - \bar{Y}(\textit{untreat},\textit{pre}))$

We can implement this via the following regression:

$$Y_i = \alpha + \tau \operatorname{Treat} imes \operatorname{Post}_{it} + \beta \operatorname{Treat}_i + \delta \operatorname{Post}_t + \varepsilon_{it}$$

To link these together, see:

$$\bar{Y}(treat, post) = \hat{\alpha} + \hat{\tau} + \hat{\beta} + \hat{\delta}$$

 $\bar{Y}(treat, pre) = \hat{\alpha} + \hat{\beta}$
 $\rightarrow \bar{Y}(treat, post) - \bar{Y}(treat, pre) = \hat{\delta} + \hat{\tau}$
and
 $\bar{Y}(untreat, post) = \hat{\alpha} + \hat{\delta}$
 $\bar{Y}(untreat, pre) = \hat{\alpha}$
 $\rightarrow \bar{Y}(untreat, post) - \bar{Y}(untreat, pre) = \hat{\delta}$

Running this regression yields $\hat{\tau} = \hat{\tau}^{DD}$

PPHA 34600

A handy table

We can implement DD via the following regression:

 $Y_i = \alpha + \tau \operatorname{Treat} \times \operatorname{Post}_{it} + \beta \operatorname{Treat}_i + \delta \operatorname{Post}_t + \varepsilon_{it}$

We can implement DD via the following regression:

$$Y_i = \alpha + \tau \operatorname{Treat} imes \operatorname{Post}_{it} + \beta \operatorname{Treat}_i + \delta \operatorname{Post}_t + \varepsilon_{it}$$

This gives us:

	Pre	Post	Difference
Treated	$\alpha + \beta + \delta + \tau$	$\alpha + \beta$	$\delta + \tau$
Untreated	$\alpha + \delta$	α	δ
Difference	$\beta + \tau$	β	au

We can add covariates:

$$Y_i = \alpha + \tau \operatorname{Treat} \times \operatorname{Post}_{it} + \beta \operatorname{Treat}_i + \delta \operatorname{Post}_t + \gamma X_{it} + \varepsilon_{it}$$

We can add covariates:

$$Y_i = \alpha + \tau \operatorname{Treat} \times \operatorname{Post}_{it} + \beta \operatorname{Treat}_i + \delta \operatorname{Post}_t + \gamma X_{it} + \varepsilon_{it}$$

We do this to:

- 1 Add precision: like the RCT, we can soak up variation
- **2** Control for important observables
 - This mixes DD with SOO

TL;DR:

- **1** We can leverage time series data for identification
- 2 This is more powerful when combined with cross-section
- **3** The resulting diff-in-diff is one of the better quasi-experiments